



## ROBOTIC DEBURRING



The deburring process **removes the metal residual stock, called “burrs”,** of a part after machining, injection or molding operation by example. This operation is **often required for security reasons, aesthetic, or necessary according to a manufacturing process.**

### How to deburr metallic parts?

There are different kinds of processes to deburr metallic parts. The choice of the method depends on the **quantity to eliminate, the form and the requested quality level.**

Manual deburring operation is well widespread for security reasons and functional reasons. However, it a painless operations. The high production rate and the lack of operators require the industries to **robotize this process.**



*Before / after edge-rounding*

### ROBOTIZED DEBURRING SOLUTION

For many years, GEBE2 implements **robotized deburring and chamfering solutions.** The equipment, that we develop, goes **from material removal until result measure.** They reproduce the gestural and sensitivity of human with abrasive or cutting tools, as well as quality and repeatability, manually impossible to reach.

In order to make our robotized cell more **autonomous** and **performing,** we integrate our compliances, tools workshop with an automated load system on the end-effectors.

**GEBE2 provides solutions on aluminum alloy, stainless steel, steel, titanium, inconel, magnesium.**

### The advantages of robotic deburring

- Optimal aesthetic appearance
- Process repeatability
- High execution speed and production
- Reduction of abrasives consumption
- Reduction of MST
- Measurement of the result

### Offline Programming

The **regularity of the tool's motion** on the part is very important to obtain **an optimal deburring quality.**

Therefore, we provide you the simulation of all possible trajectories ensure by our offline programming software (OLP). GEBE2 works with **Robotstudio, KUKASIL and Robotmaster.**



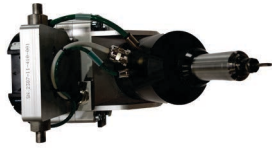
*Chamfering after machining of bores and edges*



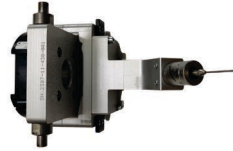
*Edge rounding by brushing*

**PRODUCT DEVELOPED BY GEBE2**

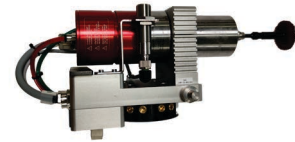
**End-effectors**



*Machining electro-spindle*



*Mechanical sensor*



*Nushing electro spindle*

**Workshops**



*Horizontal abrasive workshop*



*Vertical abrasive and cutting workshop*

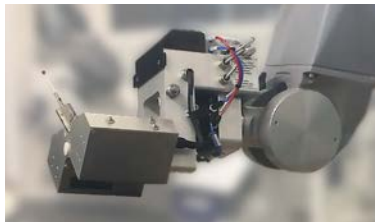


*Interior cabin*

**Recalibration systems**



*Scanner mounted on robot*

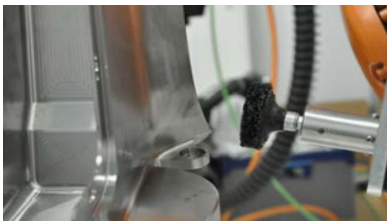


*Profilometry (2 heads) scanner*

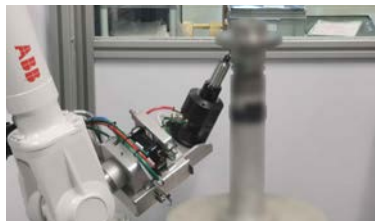


*Mechanical Probing*

**Applications**



*Deburring with abrasive tool*



*Machining*



*Robotic deburring cell*

**PROCESSES ROBOTIZATION / FEASIBILITY**

GEBE2 has a technicians' team and a demonstration cell to define parameters linked to the process robotization or feasibility realization.

